

## CHAPTER 5

# The Differential Forms of the Fundamental Laws

$$5.1 \quad 0 = \int_{c.v.} \frac{\partial \rho}{\partial t} dV + \int_{c.s.} \rho \bar{V} \cdot \hat{n} dA \quad \text{Using Gauss' theorem:}$$

$$0 = \int_{c.v.} \frac{\partial \rho}{\partial t} dV + \int_{c.v.} \bar{\nabla} \cdot (\rho \bar{V}) dV = \int_{c.v.} \left[ \frac{\partial \rho}{\partial t} + \bar{\nabla} \cdot (\rho \bar{V}) \right] dV.$$

Since this is true for all arbitrary control volumes (i.e., for all limits of integration), the integrand must be zero:

$$\frac{\partial \rho}{\partial t} + \bar{\nabla} \cdot (\rho \bar{V}) = 0.$$

This can be written in rectangular coordinates as

$$-\frac{\partial \rho}{\partial t} = \frac{\partial}{\partial x}(\rho u) + \frac{\partial}{\partial y}(\rho v) + \frac{\partial}{\partial z}(\rho w).$$

This is Eq. 5.2.2. The other forms of the continuity equation follow.

$$5.2 \quad \dot{m}_{in} - \dot{m}_{out} = \frac{\partial m_{element}}{\partial t}.$$

$$\rho v_r (rd\theta dz) - \left[ \rho v_r + \frac{\partial}{\partial r}(\rho v_r) dr \right] (r + dr) d\theta dz$$

$$+ \rho v_\theta dr dz - \left[ \rho v_\theta + \frac{\partial}{\partial \theta}(\rho v_\theta) d\theta \right] dr dz$$

$$+ \rho v_z \left( r + \frac{dr}{2} \right) d\theta dr - \left[ \rho v_z + \frac{\partial}{\partial z}(\rho v_z) dz \right] \left( r + \frac{dr}{2} \right) d\theta dr = \frac{\partial}{\partial t} \left[ \rho \left( r + \frac{dr}{2} \right) d\theta dr dz \right].$$

Subtract terms and divide by  $rd\theta dr dz$ :

$$-\frac{\rho v_r}{r} - \frac{\partial}{\partial r}(\rho v_r) \frac{r + dr}{r} - \frac{\partial}{\partial \theta}(\rho v_\theta) \frac{1}{r} - \frac{\partial}{\partial z}(\rho v_z) \frac{r + dr/2}{r} = \frac{\partial}{\partial t} \rho \frac{r + dr/2}{r}.$$

Since  $dr$  is an infinitesimal,  $(r + dr)/r = 1$  and  $(r + dr/2)/r = 1$ . Hence,

$$\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial r}(\rho v_r) + \frac{1}{r} \frac{\partial}{\partial \theta}(\rho v_\theta) + \frac{\partial}{\partial z}(\rho v_z) + \frac{1}{r} \rho v_r = 0. \quad \text{This can be put in various forms.}$$

$$\begin{aligned}
5.3 \quad \dot{m}_{in} - \dot{m}_{out} &= \frac{\partial m_{element}}{\partial t}. \\
\rho v_r (rd\theta) r \sin \theta d\phi - \left[ \rho v_r + \frac{\partial}{\partial r} (\rho v_r) dr \right] (r + dr) d\theta (r + dr) \sin \theta d\phi \\
+ \rho v_\theta dr \left( r + \frac{dr}{2} \right) \sin \theta d\phi - \left[ \rho v_\theta + \frac{\partial}{\partial \theta} (\rho v_\theta) d\theta \right] dr \left( r + \frac{dr}{2} \right) \sin \theta d\phi \\
+ \rho v_\phi dr \left( r + \frac{dr}{2} \right) d\theta - \left[ \rho v_\phi + \frac{\partial}{\partial \phi} (\rho v_\phi) d\phi \right] dr \left( r + \frac{dr}{2} \right) d\theta \\
&= \frac{\partial}{\partial t} \left[ \rho \left( r + \frac{dr}{2} \right)^2 dr d\theta \sin \theta d\phi \right]
\end{aligned}$$

Because some areas are not rectangular, we used an average length  $(r + dr/2)$ . Now, subtract some terms and divide by  $rd\theta dr$ :

$$\begin{aligned}
-\rho v_r \sin \theta - \rho v_r \sin \theta - \frac{\partial}{\partial r} (\rho v_r) \sin \theta \frac{(r + dr)^2}{r} - \frac{\partial}{\partial \theta} (\rho v_\theta) \frac{r + \frac{dr}{2}}{r} \sin \theta \\
- \frac{\partial}{\partial \phi} (\rho v_\phi) \frac{r + \frac{dr}{2}}{r} = \frac{\partial \rho}{\partial t} \frac{\left( r + \frac{dr}{2} \right)^2}{r} \sin \theta
\end{aligned}$$

Since  $dr$  is infinitesimal  $(r + dr)^2 / r = r$  and  $(r + dr/2) / r = 1$ . Divide by  $r \sin \theta$  and there results

$$\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial r} (\rho v_r) + \frac{1}{r} \frac{\partial}{\partial \theta} (\rho v_\theta) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} (\rho v_\phi) + \frac{2}{r} \rho v_r = 0$$

5.4 For a steady flow  $\frac{\partial \rho}{\partial t} = 0$ . Then, with  $v = w = 0$  Eq. 5.2.2 yields

$$\frac{\partial}{\partial x} (\rho u) = 0 \quad \text{or} \quad \underline{\rho \frac{du}{dx} + u \frac{d\rho}{dx} = 0}.$$

Partial derivatives are not used since there is only one independent variable.

5.5 Since the flow is incompressible  $\frac{D\rho}{Dt} = 0$ . This gives

$$\therefore \bar{\nabla} p = \frac{\rho}{r} \hat{i}_r + \frac{1}{r} \frac{\rho}{\sin \theta} \hat{i}_\theta = \frac{200r}{r^3} \left[ \frac{1}{r^2} - \cos 2\theta \right] \hat{i}_r - \frac{200r}{r^3} \sin 2\theta \hat{i}_\theta \quad \text{or}$$

$$u \frac{\partial \rho}{\partial x} + w \frac{\partial \rho}{\partial z} = 0.$$

$$\text{Also, } \bar{\nabla} \cdot \bar{V} = 0, \quad \text{or} \quad \underline{\frac{\partial u}{\partial x} + \frac{\partial w}{\partial z} = 0}.$$

5.6 Given:  $\frac{\partial}{\partial t} = 0$ ,  $\frac{\partial \rho}{\partial z} \neq 0$ . Since water can be considered to be incompressible, we demand that  $\frac{D\rho}{Dt} = 0$ .  $\therefore u \frac{\partial \rho}{\partial x} + w \frac{\partial \rho}{\partial z} = 0$ , assuming the  $x$ -direction to be in the direction of flow. Also, we demand that  $\bar{\nabla} \cdot \bar{V} = 0$ , or  $\frac{\partial u}{\partial x} + \frac{\partial w}{\partial z} = 0$ .

5.7 We can use the ideal gas law,  $\rho = \frac{p}{RT}$ . Then, the continuity equation  $\frac{D\rho}{Dt} = -\rho \bar{\nabla} \cdot \bar{V}$  becomes, assuming  $RT$  to be constant,  $\frac{1}{RT} \frac{Dp}{Dt} = -\frac{p}{RT} \bar{\nabla} \cdot \bar{V}$  or  $\frac{1}{p} \frac{Dp}{Dt} = -\bar{\nabla} \cdot \bar{V}$ .

5.8 a) Use cylindrical coordinates with  $v_\theta = v_z = 0$ :

$$\frac{1}{r} \frac{\partial}{\partial r}(rv_r) = 0$$

Integrate:

$$rv_r = C. \quad \therefore v_r = \frac{C}{r}$$

b) Use spherical coordinates with  $v_\theta = v_\phi = 0$ :

$$\frac{1}{r^2} \frac{\partial}{\partial r}(r^2 v_r) = 0$$

Integrate:

$$r^2 v_r = C. \quad \therefore v_r = \frac{C}{r^2}$$

5.9  $\frac{Dp}{Dt} = -\rho \bar{\nabla} \cdot \bar{V} = -\rho \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) = -2.3(200 \times 1 + 400 \times 1) = \underline{\underline{-1380 \frac{\text{kg}}{\text{m}^3 \cdot \text{s}}}}$

5.10 In a plane flow,  $u = u(x, y)$  and  $v = v(x, y)$ . Continuity demands that  $\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$ .

If  $u = \text{const}$ , then  $\frac{\partial u}{\partial x} = 0$  and hence  $\frac{\partial v}{\partial y} = 0$ . Thus,  $v = \text{const}$  also.

5.11 If  $u = C_1$  and  $v = C_2$ , the continuity equation provides, for an incompressible flow,

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0. \quad \therefore \frac{\partial w}{\partial z} = 0 \text{ and } w = C_3.$$

The z-component of velocity  $w$  is also constant.

We also have

$$\frac{D\rho}{Dt} = 0 = \frac{\partial \rho}{\partial t} + u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z}$$

The density may vary with  $x, y, z$  and  $t$ . It is not, necessarily, constant.

$$5.12 \quad \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0. \quad \therefore A + \frac{\partial v}{\partial y} = 0. \quad \therefore v(x, y) = -Ay + f(x).$$

$$\text{But, } v(x, 0) = 0 = f(x). \quad \therefore \underline{v = -Ay}.$$

$$5.13 \quad \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0. \quad \therefore \frac{\partial v}{\partial y} = -\frac{\partial u}{\partial x} = -\frac{(x^2 + y^2)5 - 5x(2x)}{(x^2 + y^2)^2} = -\frac{5x^2 - 5y^2}{(x^2 + y^2)^2}$$

$$\therefore v(x, y) = \int \frac{5y^2 - 5x^2}{(x^2 + y^2)^2} dy + f(x) = \frac{5y}{x^2 + y^2} + f(x). \quad f(x) = 0. \quad \therefore \underline{v = \frac{5y}{x^2 + y^2}}.$$

$$5.14 \quad \text{From Table 5.1: } \frac{1}{r} \frac{\partial}{\partial r}(rv_r) = -\frac{1}{r} \frac{\partial v_\theta}{\partial \theta} = -\frac{1}{r} \left( 10 + \frac{.4}{r^2} \right) \sin \theta.$$

$$\therefore rv_r = \int \left( 10 + \frac{.4}{r^2} \right) \sin \mathbf{q} dr + f(\mathbf{q}) = \left( 10r - \frac{.4}{r} \right) \sin \mathbf{q} + f(\mathbf{q}).$$

$$.2v_r(.2, \mathbf{q}) = \left( 10 \times .2 - \frac{.4}{.2} \right) \sin \mathbf{q} + f(\mathbf{q}) = 0. \quad \therefore f(\mathbf{q}) = 0.$$

$$\therefore \underline{v_r = \left( 10 - \frac{0.4}{r^2} \right) \sin \mathbf{q}}.$$

$$5.15 \quad \text{From Table 5.1: } \frac{1}{r} \frac{\partial}{\partial r}(rv_r) = -\frac{1}{r} \frac{\partial v_\theta}{\partial \theta} = \frac{-20}{r} \left( 1 + \frac{1}{r^2} \right) \cos \theta.$$

$$\therefore rv_r = \int -20 \left( 1 + \frac{1}{r^2} \right) \cos \mathbf{q} dr + f(\mathbf{q}) = -20 \left( r - \frac{1}{r} \right) \cos \mathbf{q} + f(\mathbf{q}).$$

$$v_r(1, \mathbf{q}) = -20(1 - 1) \cos \mathbf{q} + f(\mathbf{q}) = 0. \quad \therefore f(\mathbf{q}) = 0.$$

$$\therefore \underline{v_r = -20 \left( 1 - \frac{1}{r^2} \right) \cos \mathbf{q}}.$$

5.16 From Table 5.1, spherical coordinates:  $\frac{1}{r^2} \frac{\partial}{\partial r}(r^2 v_r) = -\frac{1}{r \sin \theta} \frac{\partial}{\partial \theta}(v_\theta \sin \theta)$ .

$$\therefore \frac{1}{r^2} \frac{\partial}{\partial r}(r^2 v_r) = \frac{1}{r \sin \theta} \left(10 + \frac{40}{r^3}\right) 2 \sin \theta \cos \theta.$$

$$\therefore r^2 v_r = \int r \left(10 + \frac{40}{r^3}\right) 2 \cos \theta dr + f(\theta) = \left(10r^2 - \frac{80}{r}\right) \cos \theta + f(\theta)$$

$$4v_r(2, \theta) = \left(10 \times 2^2 - \frac{80}{2}\right) \cos \theta + f(\theta) = 0. \quad \therefore f(\theta) = 0.$$

$$\therefore v_r = \underline{\left(10 - \frac{80}{r^3}\right) \cos \theta}.$$

5.17 Continuity:  $\frac{\partial}{\partial x}(\rho u) = 0. \quad \therefore \rho \frac{du}{dx} + u \frac{d\rho}{dx} = 0.$

$$r = \frac{p}{RT} = \frac{18 \times 144}{1716 \times 500} = 0.00302 \frac{\text{slug}}{\text{ft}^3}. \quad \frac{du}{dx} = \frac{526 - 453}{2 \times 2 / 12} = 219 \text{ fps / ft.}$$

$$\therefore \frac{dr}{dx} = -\frac{r}{u} \frac{du}{dx} = -\frac{.00302}{486} \times 219 = \underline{-0.00136 \text{ slug / ft}^4}.$$

5.18  $\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0. \quad \frac{\partial}{\partial x}[-20(1 - e^{-x})] = -20e^{-x}$

Hence, in the vicinity of the x-axis:

$$\frac{\partial v}{\partial y} = 20e^{-x} \text{ and } v = 20ye^{-x} + C.$$

But  $v = 0$  if  $y = 0. \quad \therefore C = 0.$

$$v = 20ye^{-x} = 20(0.2)e^{-2} = \underline{0.541 \text{ m / s}}$$

5.19  $\frac{1}{r} \frac{\partial}{\partial r}(rv_r) + \frac{\partial v_z}{\partial z} = 0. \quad \frac{\partial}{\partial z}[-20(1 - e^{-z})] = -20e^{-z}$

Hence, in the vicinity of the z-axis:

$$\frac{1}{r} \frac{\partial}{\partial r}(rv_r) = 20e^{-z} \text{ and } rv_r = \frac{r^2}{2} 20e^{-z} + C.$$

But  $v_r = 0$  if  $r = 0. \quad \therefore C = 0.$

$$v_r = 10re^{-z} = 10(0.2)e^{-2} = \underline{0.271 \text{ m / s}}$$

5.20 The velocity is zero at the stagnation point. Hence,

$$0 = 10 - \frac{40}{R^2}. \quad \therefore \underline{R = 2 \text{ m}}$$

The continuity equation for this plane flow is  $\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0.$  Using  $\frac{\partial u}{\partial x} = 80x^{-3},$

we see that  $\frac{\partial v}{\partial y} = -80x^{-3}$  near the  $x$ -axis. Consequently, for small  $\Delta y$ ,

$$\Delta v = -80x^{-3}\Delta y \quad \text{so that} \quad v = -80(-3)^{-3}(0.1) = \underline{0.296 \text{ m / s}}$$

5.21 The velocity is zero at the stagnation point. Hence

$$0 = \frac{40}{R^2} - 10. \quad \therefore \underline{R = 2 \text{ m}}$$

$$\frac{1}{r^2} \frac{\partial}{\partial r}(r^2 v_r) = \frac{1}{r^2} \frac{\partial}{\partial r}(40 - 10r^2) = -\frac{20}{r}.$$

Near the negative  $x$ -axis continuity provides us with

$$\frac{1}{r \sin \theta} \frac{\partial}{\partial \theta}(v_\theta \sin \theta) = \frac{20}{r}.$$

Integrate, letting  $q = 0$  from the  $y$ -axis:

$$v_q \sin q = -20 \cos q + C$$

Since  $v_q = 0$  when  $q = 90^\circ$ ,  $C = 0$ . Then, with  $\alpha = \tan^{-1} \frac{0.1}{3} = 1.909^\circ$ ,

$$v_q = -20 \frac{\cos q}{\sin q} = -20 \frac{\cos 88.091}{\sin 88.091} = -20 \frac{0.0333}{0.999} = \underline{0.667 \text{ m / s}}$$

5.22 Continuity:  $\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0. \quad \therefore \frac{\Delta v}{\Delta y} = -\frac{\Delta u}{\Delta x} = -\frac{13.5 - 11.3}{2 \times 0.005} = -220 \frac{\text{m / s}}{\text{m}}$ .

$$\therefore \Delta v = v - 0 = -220 \Delta y. \quad \therefore v = -220 \times 0.004 = \underline{-0.88 \text{ m / s}}$$

b)  $a_x = u \frac{\partial u}{\partial x} = 12.6 \times (+220) = \underline{2772 \text{ m / s}^2}$ .

5.23  $\Sigma F_y = ma_y$ . For the fluid particle occupying the volume of Fig. 5.3:

$$\begin{aligned} & \left( \tau_{yy} + \frac{\partial \tau_{yy}}{\partial y} \frac{dy}{2} \right) dx dz + \left( \tau_{zy} + \frac{\partial \tau_{zy}}{\partial z} \frac{dz}{2} \right) dx dy + \left( \tau_{xy} + \frac{\partial \tau_{xy}}{\partial x} \frac{dx}{2} \right) dy dz \\ & - \left( \tau_{yy} - \frac{\partial \tau_{yy}}{\partial y} \frac{dy}{2} \right) dx dz - \left( \tau_{zy} - \frac{\partial \tau_{zy}}{\partial z} \frac{dz}{2} \right) dx dy - \left( \tau_{xy} - \frac{\partial \tau_{xy}}{\partial x} \frac{dx}{2} \right) dy dz \\ & + \rho g_y dx dy dz = \rho dx dy dz \frac{Dv}{Dt} \end{aligned}$$

Dividing by  $dx dy dz$ , and adding and subtracting terms:

$$\frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \tau_{yy}}{\partial y} + \frac{\partial \tau_{zy}}{\partial z} + \rho g_y = \rho \frac{Dv}{Dt}.$$

5.24 Check continuity:

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = \frac{(x^2 + y^2)10 - 10x(2x)}{(x^2 + y^2)^2} + \frac{(x^2 + y^2)10 - 10y(2y)}{(x^2 + y^2)^2} = 0.$$

Thus, it is a possible flow. For a frictionless flow, Euler's Eqs. 5.3.7 give, with  $g_x = g_y = 0$ :

$$\begin{aligned} r u \frac{\partial u}{\partial x} + r v \frac{\partial u}{\partial y} &= -\frac{\partial p}{\partial x} \\ \therefore \frac{\partial p}{\partial x} &= -r \frac{10x}{x^2 + y^2} \frac{10y^2 - 10x^2}{(x^2 + y^2)^2} - r \frac{10y}{x^2 + y^2} \frac{-20xy}{(x^2 + y^2)^2} = r \frac{100(x^2 + y^2)y}{(x^2 + y^2)^3} \\ r u \frac{\partial v}{\partial x} + r v \frac{\partial v}{\partial y} &= -\frac{\partial p}{\partial y} \\ \therefore \frac{\partial p}{\partial y} &= -r \frac{10x}{x^2 + y^2} \frac{-20xy}{(x^2 + y^2)^2} - r \frac{10y}{x^2 + y^2} \frac{10x^2 - 10y^2}{(x^2 + y^2)^2} = r \frac{100(x^2 + y^2)y}{(x^2 + y^2)^3} \\ \therefore \bar{\nabla} p &= \frac{\partial p}{\partial x} \hat{i} + \frac{\partial p}{\partial y} \hat{j} = \frac{100x\mathbf{r}}{(x^2 + y^2)^2} \hat{i} + \frac{100y\mathbf{r}}{(x^2 + y^2)^2} \hat{j} = \frac{100\mathbf{r}}{(x^2 + y^2)^2} (x\hat{i} + y\hat{j}). \end{aligned}$$

5.25 Check continuity (cylindrical coord from Table 5.1):

$$\frac{1}{r} \frac{\partial}{\partial r} (rv_r) + \frac{1}{r} \frac{\partial v_\theta}{\partial \theta} = \frac{10}{r} \left(1 + \frac{1}{r^2}\right) \cos \theta + \frac{-10}{r} \left(1 + \frac{1}{r^2}\right) \cos \theta = 0. \quad \therefore \text{It is a possible}$$

flow. For Euler's Eqs. (let  $n = 0$  in the momentum eqns of Table 5.1) in cylindrical coord:

$$\begin{aligned} \frac{\partial p}{\partial r} &= r \frac{v_\theta^2}{r} - r v_r \frac{\partial v_r}{\partial r} - r \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} = \frac{100\mathbf{r}}{r} \left(1 + \frac{1}{r^2}\right)^2 \sin^2 \mathbf{q} - 10\mathbf{r} \left(1 - \frac{1}{r^2}\right) \cos^2 \mathbf{q} \left(\frac{20}{r^3}\right) \\ &\quad - \frac{10\mathbf{r}}{r} \left(1 + \frac{1}{r^2}\right) \sin^2 \mathbf{q} \left(10 - \frac{10}{r^2}\right). \\ \frac{1}{r} \frac{\partial p}{\partial \theta} &= -r \frac{v_r v_\theta}{r} - r v_r \frac{\partial v_\theta}{\partial r} - r \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} = \frac{100\mathbf{r}}{r} \left(1 - \frac{1}{r^4}\right) \sin \mathbf{q} \cos \mathbf{q} \\ &\quad - 10\mathbf{r} \left(1 - \frac{1}{r^2}\right) \cos \mathbf{q} \sin \mathbf{q} \left(\frac{20}{r^3}\right) - \frac{100\mathbf{r}}{r} \left(1 + \frac{1}{r^2}\right)^2 \sin \mathbf{q} \cos \mathbf{q}. \\ \therefore \bar{\nabla} p &= \frac{\partial p}{\partial r} \hat{i}_r + \frac{1}{r} \frac{\partial p}{\partial \theta} \hat{i}_\theta = \frac{200\mathbf{r}}{r^3} \left[ \frac{1}{r^2} - \cos 2\mathbf{q} \right] \hat{i}_r - \frac{200\mathbf{r}}{r^3} \sin 2\mathbf{q} \hat{i}_\theta \end{aligned}$$

5.26 This is an involved problem. Follow the steps of Problem 5.25. Good luck!

$$\begin{aligned} \frac{\partial p}{\partial r} &= \rho \frac{(v_\theta^2 + v_\phi^2)}{r} - \rho v_r \frac{\partial v_r}{\partial r} - \rho \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} \\ \frac{1}{r} \frac{\partial p}{\partial \theta} &= -\rho \frac{(v_r v_\theta)}{r} - \rho v_r \frac{\partial v_\theta}{\partial r} - \rho \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} \end{aligned}$$

$$5.27 \quad \therefore \bar{p} = p - \left( \frac{2m}{3} + 1 \right) \bar{\nabla} \cdot \bar{V}. \quad \therefore \bar{p} - p = - \left( \frac{2m}{3} + 1 \right) \bar{\nabla} \cdot \bar{V}.$$

$$\frac{\partial \hat{s}}{\partial s} \cong \frac{\Delta \hat{s}}{\Delta s} = - \frac{\Delta \alpha \hat{n}}{R \Delta \alpha} = - \frac{\hat{n}}{R}.$$

$$\frac{\partial \hat{s}}{\partial t} \cong \frac{\Delta \hat{s}}{\Delta t} = \frac{\hat{n} \Delta \theta}{\Delta t} = \hat{n} \frac{\partial \theta}{\partial t}.$$

$$\therefore \frac{D\bar{V}}{Dt} = \left( \frac{\nabla V}{\nabla t} + V \frac{\nabla V}{\nabla s} \right) \hat{s} + \left( V \frac{\nabla q}{\nabla t} - \frac{V^2}{R} \right) \hat{n}.$$

For steady flow, the normal acc. is  $\left( -\frac{V^2}{R} \right)$ , the tangential acc. is  $V \frac{\partial V}{\partial s}$ .

5.28 For a rotating reference frame (see Eq. 3.2.15), we must add the terms due to  $\bar{\Omega}$ . Thus, Euler's equation becomes

$$\mathbf{r} \left( \frac{D\bar{V}}{Dt} + 2\bar{\Omega} \times \bar{V} + \bar{\Omega} \times (\bar{\Omega} \times \bar{r}) + \frac{d\bar{\Omega}}{dt} \times \bar{r} \right) = -\bar{\nabla} p - \mathbf{r} \bar{g}.$$

$$5.29 \quad t_{xx} = -p + 2m \frac{\nabla u}{\nabla x} + 1 \bar{\nabla} \cdot \bar{V} = -30 \text{ psi.}$$

$$t_{yy} = t_{zz} = -p = -30 \text{ psi.}$$

$$t_{xy} = m \left( \frac{\nabla u}{\nabla y} + \frac{\nabla v}{\nabla x} \right) = 10^{-5} \left[ 30 - 1440 \times \frac{.1}{12} \right] = 18 \times 10^{-5} \text{ psf.}$$

$$t_{xz} = t_{yz} = 0. \quad \frac{t_{xy}}{t_{xx}} = \frac{18 \times 10^{-5}}{30 \times 144} = 4.17 \times 10^{-8}.$$

$$5.30 \quad \frac{\nabla v}{\nabla y} = - \frac{\nabla u}{\nabla x} = \frac{16y}{Cx^{9/5}} - \frac{16y^2}{C^2 x^{13/5}}. \quad \therefore v(x, y) = \frac{8y^2}{Cx^{9/5}} - \frac{16y^3}{3C^2 x^{13/5}} + f(x).$$

$$v(x, 0) = 0. \quad \therefore f(x) = 0. \quad 8 = C 1000^{4/5}. \quad \therefore C = 0.0318.$$

$$\therefore u(x, y) = 629yx^{-4/5} - 9890y^2x^{-8/5}.$$

$$v(x, y) = 252y^2x^{-9/5} - 5270y^3x^{-13/5}.$$

$$\tau_{xx} = -p + 2\mu \frac{\partial u}{\partial x} = -100 + 0 = -100 \text{ kPa.}$$

$$t_{yy} = t_{zz} = -p = -100 \text{ kPa.}$$

$$t_{xy} = m \left( \frac{\nabla u}{\nabla y} + \frac{\nabla v}{\nabla x} \right) = 2 \times 10^{-5} \left[ 629 \times 1000^{-4/5} \right] = 5.01 \times 10^{-5} \text{ Pa.}$$

$$t_{xz} = t_{yz} = 0.$$



$$\begin{aligned}
5.31 \quad \frac{Du}{Dt} &= \frac{\cancel{\rho}}{\cancel{\rho}} \frac{d}{dt} + \left( u \frac{\cancel{\rho}}{\cancel{\rho} x} + v \frac{\cancel{\rho}}{\cancel{\rho} y} + w \frac{\cancel{\rho}}{\cancel{\rho} z} \right) u = (\vec{V} \cdot \vec{\nabla})u. \\
\frac{Dv}{Dt} &= \frac{\cancel{\rho}}{\cancel{\rho}} \frac{d}{dt} + \left( u \frac{\cancel{\rho}}{\cancel{\rho} x} + v \frac{\cancel{\rho}}{\cancel{\rho} y} + w \frac{\cancel{\rho}}{\cancel{\rho} z} \right) v = (\vec{V} \cdot \vec{\nabla})v. \\
\frac{Dw}{Dt} &= \frac{\cancel{\rho}}{\cancel{\rho}} \frac{d}{dt} + \left( u \frac{\cancel{\rho}}{\cancel{\rho} x} + v \frac{\cancel{\rho}}{\cancel{\rho} y} + w \frac{\cancel{\rho}}{\cancel{\rho} z} \right) w = (\vec{V} \cdot \vec{\nabla})w \\
\therefore \frac{D\vec{V}}{Dt} &= \frac{Du}{Dt} \hat{i} + \frac{Dv}{Dt} \hat{j} + \frac{Dw}{Dt} \hat{k} = \vec{V} \cdot \vec{\nabla} (u\hat{i} + v\hat{j} + w\hat{k}) = (\vec{V} \cdot \vec{\nabla})\vec{V}.
\end{aligned}$$

5.32 Follow the steps that lead to Eq. 5.3.17 and add the term due to compressible effects:

$$\begin{aligned}
\mathbf{r} \frac{D\vec{V}}{Dt} &= -\vec{\nabla}p + \mathbf{r}\bar{g} + \mathbf{m}\bar{V}^2\vec{V} + \frac{\mathbf{m}}{3} \frac{\cancel{\rho}}{\cancel{\rho} x} \vec{\nabla} \cdot \vec{V} \hat{i} + \frac{\mathbf{m}}{3} \frac{\cancel{\rho}}{\cancel{\rho} y} \vec{\nabla} \cdot \vec{V} \hat{j} + \frac{\mathbf{m}}{3} \frac{\cancel{\rho}}{\cancel{\rho} z} \vec{\nabla} \cdot \vec{V} \hat{k} \\
&= -\vec{\nabla}p + \rho\bar{g} + \mu\nabla^2\vec{V} + \frac{\mu}{3} \left( \frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k} \right) \vec{\nabla} \cdot \vec{V} \\
\therefore \mathbf{r} \frac{D\vec{V}}{Dt} &= \underline{-\vec{\nabla}p + \mathbf{r}\bar{g} + \mathbf{m}\bar{V}^2\vec{V} + \frac{\mathbf{m}}{3} \vec{\nabla}(\vec{\nabla} \cdot \vec{V})}.
\end{aligned}$$

5.33 If  $u=u(y)$ , then continuity demands that  $\frac{\partial v}{\partial y} = 0$ .  $\therefore v = C$ .

But, at  $y=0$  (the lower plate)  $v=0$ .  $\therefore C = 0$ , and  $v(x, y) = 0$ .

$$\begin{aligned}
\therefore \mathbf{r} \frac{Du}{Dt} &= \mathbf{r} \left( \frac{\cancel{\rho} u}{\cancel{\rho} t} + u \frac{\cancel{\rho} u}{\cancel{\rho} x} + v \frac{\cancel{\rho} u}{\cancel{\rho} y} + w \frac{\cancel{\rho} u}{\cancel{\rho} z} \right) = -\frac{\cancel{\rho} p}{\cancel{\rho} x} + \mathbf{r}g_x + \mathbf{m} \left( \frac{\cancel{\rho}^2 u}{\cancel{\rho} x^2} + \frac{\cancel{\rho}^2 u}{\cancel{\rho} y^2} + \frac{\cancel{\rho}^2 u}{\cancel{\rho} z^2} \right) \\
\therefore 0 &= \underline{-\frac{\partial p}{\partial x} + \mu \frac{\partial^2 u}{\partial y^2}}. \\
\mathbf{r} \frac{Dv}{Dt} &= 0 = \underline{-\frac{\cancel{\rho} p}{\cancel{\rho} y}}. \\
\rho \frac{Dw}{Dt} &= 0 = \underline{-\frac{\partial p}{\partial z} + \rho(-g)}. \quad \therefore 0 = \underline{-\frac{\partial p}{\partial z} - \rho g}.
\end{aligned}$$

5.34 Continuity:  $\frac{\cancel{\rho}}{\cancel{\rho} r} (rv_r) = 0$ .  $\therefore rv_r = C$ . At  $r = 0$ ,  $v_r \neq \infty$ .  $\therefore C = 0$ .

$$\begin{aligned}
\frac{Dv_r}{Dt} &= 0 = \underline{-\frac{1}{r} \frac{\cancel{\rho} p}{\cancel{\rho} r}}. \\
\frac{Dv_\theta}{Dt} &= 0 = \underline{-\frac{1}{rr} \frac{\cancel{\rho} p}{\cancel{\rho} r}}.
\end{aligned}$$

$$\mathbf{r} \frac{Dv_z}{Dt} = \mathbf{r} \left( \frac{\mathcal{I}v_z}{\mathcal{I}t} + v_r \frac{\mathcal{I}v_z}{\mathcal{I}r} + \frac{v_\theta}{r} \frac{\mathcal{I}v_z}{\mathcal{I}q} + v_z \frac{\mathcal{I}v_z}{\mathcal{I}z} \right) = -\frac{\mathcal{I}p}{\mathcal{I}z} + \mathbf{m} \left( \frac{\mathcal{I}^2 v_z}{\mathcal{I}r^2} + \frac{1}{r} \frac{\mathcal{I}v_z}{\mathcal{I}r} + \frac{1}{r^2} \frac{\mathcal{I}^2 v_z}{\mathcal{I}q^2} + \frac{\mathcal{I}^2 v_z}{\mathcal{I}z^2} \right)$$

$$\therefore 0 = -\frac{\partial p}{\partial z} + \mu \left( \frac{\partial^2 v_z}{\partial r^2} + \frac{1}{r} \frac{\partial v_z}{\partial r} \right)$$

5.35 Continuity:  $\frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_r) = 0$ .  $\therefore r^2 v_r = C$ . At  $r = r_1$ ,  $v_r = 0$ .  $\therefore C = 0$ .

$$-\frac{v_\theta^2}{r} \mathbf{r} = -\frac{\mathcal{I}p}{\mathcal{I}r} + \mathbf{m} \left( -\frac{2v_\theta}{r^2} \cot q \right)$$

$$0 = -\frac{1}{r} \frac{\mathcal{I}p}{\mathcal{I}q} + \mathbf{m} \left[ \frac{1}{r^2} \frac{\mathcal{I}}{\mathcal{I}r} \left( r^2 \frac{\mathcal{I}v_\theta}{\mathcal{I}r} \right) - \frac{v_\theta}{r^2 \sin^2 q} \right]$$

$$0 = -\frac{1}{r \sin \theta} \frac{\partial p}{\partial \phi}$$

5.36 For an incompressible flow  $\bar{\nabla} \cdot \bar{V} = 0$ . Substitute Eqs. 5.3.10 into Eq. 5.3.2 and 5.3.3:

$$\rho \frac{Du}{Dt} = \frac{\partial}{\partial x} \left( -p + 2\mu \frac{\partial u}{\partial x} \right) + \frac{\partial}{\partial y} \mu \left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) + \frac{\partial}{\partial z} \mu \left( \frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} \right) + \rho g_x$$

$$= -\frac{\partial p}{\partial x} + \mu \frac{\partial^2 u}{\partial x^2} + \mu \frac{\partial^2 u}{\partial y^2} + \mu \frac{\partial^2 u}{\partial z^2} + \mu \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + \rho g_x$$

$$\therefore \rho \frac{Du}{Dt} = -\frac{\partial p}{\partial x} + \mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right) + \rho g_x$$

$$\mathbf{r} \frac{Dv}{Dt} = \frac{\mathcal{I}}{\mathcal{I}x} \mathbf{m} \left( \frac{\mathcal{I}u}{\mathcal{I}y} + \frac{\mathcal{I}v}{\mathcal{I}x} \right) + \frac{\mathcal{I}}{\mathcal{I}y} \left( -p + 2\mathbf{m} \frac{\mathcal{I}v}{\mathcal{I}y} \right) + \frac{\mathcal{I}}{\mathcal{I}z} \mathbf{m} \left( \frac{\mathcal{I}v}{\mathcal{I}z} + \frac{\mathcal{I}w}{\mathcal{I}y} \right) + \mathbf{r} g_y$$

$$= -\frac{\partial p}{\partial y} + \mu \frac{\partial^2 v}{\partial x^2} + \mu \frac{\partial^2 v}{\partial y^2} + \mu \frac{\partial^2 v}{\partial z^2} + \mu \frac{\partial}{\partial y} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + \rho g_y$$

$$\therefore \rho \frac{Dv}{Dt} = -\frac{\partial p}{\partial y} + \mu \left( \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2} \right) + \rho g_y$$

$$\mathbf{r} \frac{Dw}{Dt} = \frac{\mathcal{I}}{\mathcal{I}x} \mathbf{m} \left( \frac{\mathcal{I}u}{\mathcal{I}z} + \frac{\mathcal{I}w}{\mathcal{I}x} \right) + \frac{\mathcal{I}}{\mathcal{I}y} \mathbf{m} \left( \frac{\mathcal{I}v}{\mathcal{I}z} + \frac{\mathcal{I}w}{\mathcal{I}y} \right) + \frac{\mathcal{I}}{\mathcal{I}z} \left( -p + 2\mathbf{m} \frac{\mathcal{I}w}{\mathcal{I}z} \right) + \mathbf{r} g_z$$

$$= -\frac{\partial p}{\partial z} + \mu \frac{\partial^2 w}{\partial x^2} + \mu \frac{\partial^2 w}{\partial y^2} + \mu \frac{\partial^2 w}{\partial z^2} + \mu \frac{\partial}{\partial z} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + \rho g_z$$

$$\therefore \rho \frac{Dw}{Dt} = -\frac{\partial p}{\partial z} + \mu \left( \frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2} \right) + \rho g_z.$$

5.37 If we substitute the constitutive equations (5.3.10) into Eqs. 5.3.2 and 5.3.3., with  $\mathbf{m} = \mathbf{m}(x, y, z)$  we arrive at

$$\mathbf{r} \frac{Du}{Dt} = -\frac{\mathcal{I} p}{\mathcal{I} x} + \mathbf{r} g_x + \mathbf{m} \left( \frac{\mathcal{I}^2 u}{\mathcal{I} x^2} + \frac{\mathcal{I}^2 u}{\mathcal{I} y^2} + \frac{\mathcal{I}^2 u}{\mathcal{I} z^2} \right) + 2 \frac{\mathcal{I} \mathbf{m} \mathcal{I} u}{\mathcal{I} x \mathcal{I} x} + \frac{\mathcal{I} \mathbf{m}}{\mathcal{I} y} \left( \frac{\mathcal{I} u}{\mathcal{I} y} + \frac{\mathcal{I} v}{\mathcal{I} x} \right) + \frac{\mathcal{I} \mathbf{m}}{\mathcal{I} z} \left( \frac{\mathcal{I} u}{\mathcal{I} z} + \frac{\mathcal{I} w}{\mathcal{I} x} \right)$$

5.38 If plane flow is only parallel to the plate,  $v = w = 0$ . Continuity then demands that  $\partial u / \partial x = 0$ . The first equation of (5.3.14) simplifies to

$$\mathbf{r} \left( \frac{\mathcal{I} u}{\mathcal{I} t} + u \frac{\mathcal{I} \mathcal{I}}{\mathcal{I} x} + \cancel{\mathcal{I} u} + \cancel{\mathcal{I} u} \frac{\mathcal{I} u}{\mathcal{I} z} \right) = -\frac{\mathcal{I} p}{\mathcal{I} x} + \mathbf{r} g_x + \mathbf{m} \left( \frac{\mathcal{I}^2 u}{\mathcal{I} x^2} + \frac{\mathcal{I}^2 u}{\mathcal{I} y^2} + \frac{\mathcal{I}^2 u}{\mathcal{I} z^2} \right)$$

$$\mathbf{r} \frac{\mathcal{I} u}{\mathcal{I} t} = \mathbf{m} \frac{\mathcal{I}^2 u}{\mathcal{I} y^2}$$

We assumed  $g$  to be in the  $y$ -direction, and since no forcing occurs other than due to the motion of the plate, we let  $\partial p / \partial x = 0$ .

5.39 From Eqs. 5.3.10,  $-\frac{\tau_{xx} + \tau_{yy} + \tau_{zz}}{3} = p - \frac{2\mu}{3} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) - \lambda \bar{\nabla} \cdot \bar{V}$ .

$$\therefore \bar{p} = p - \left( \frac{2\mathbf{m}}{3} + \mathbf{1} \right) \bar{\nabla} \cdot \bar{V}. \quad \therefore \bar{p} - p = -\left( \frac{2\mathbf{m}}{3} + \mathbf{1} \right) \bar{\nabla} \cdot \bar{V}.$$

5.40  $(\bar{V} \cdot \nabla) \bar{V} = \left( u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) (u \hat{i} + v \hat{j} + w \hat{k})$

$$\nabla \times (\bar{V} \cdot \nabla) \bar{V} = \left[ \frac{\partial}{\partial y} \left( u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} \right) - \frac{\partial}{\partial z} \left( u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} \right) \right] \hat{i}$$

$$+ \left[ \frac{\partial}{\partial z} \left( u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right) - \frac{\partial}{\partial x} \left( u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} \right) \right] \hat{j}$$

$$+ \left[ \frac{\partial}{\partial x} \left( u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} \right) - \frac{\partial}{\partial y} \left( u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right) \right] \hat{k}$$

Use the definition of vorticity:  $\bar{\omega} = \left( \frac{\partial w}{\partial y} - \frac{\partial v}{\partial z} \right) \hat{i} + \left( \frac{\partial u}{\partial z} - \frac{\partial w}{\partial x} \right) \hat{j} + \left( \frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right) \hat{k}$

$$(\vec{w} \cdot \nabla) \vec{V} = \left[ \left( \frac{\partial w}{\partial y} - \frac{\partial v}{\partial z} \right) \frac{\partial}{\partial x} + \left( \frac{\partial u}{\partial z} - \frac{\partial w}{\partial x} \right) \frac{\partial}{\partial y} + \left( \frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right) \frac{\partial}{\partial z} \right] (u\hat{i} + v\hat{j} + w\hat{k})$$

$$(\vec{V} \cdot \nabla) \vec{w} = \left[ u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right] \left[ \left( \frac{\partial w}{\partial y} - \frac{\partial v}{\partial z} \right) \hat{i} + \left( \frac{\partial u}{\partial z} - \frac{\partial w}{\partial x} \right) \hat{j} + \left( \frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right) \hat{k} \right]$$

Expand the above, collect like terms, and compare coefficients of  $\hat{i}$ ,  $\hat{j}$ , and  $\hat{k}$ .

- 5.41 Studying the vorticity components of Eq. 3.2.21, we see that  $w_z = -\frac{\partial u}{\partial y}$  is the only vorticity component of interest. The third equation of Eq. 5.3.24 then simplifies to

$$\frac{Dw_z}{Dt} = \mathbf{n} \nabla^2 w_z$$

$$= \mathbf{n} \frac{\partial^2 w_z}{\partial y^2}$$

since changes normal to the plate are much larger than changes along the plate, i.e.,  $\frac{\partial w_z}{\partial y} \gg \frac{\partial w_z}{\partial x}$ .

- 5.42 If viscous effects are negligible, as they are in a short section, Eq. 5.3.25 reduces to

$$\frac{Dw_z}{Dt} = 0$$

that is, there is no change in vorticity (along a streamline) between sections 1 and 2. Since (see Eq. 3.2.21), at section 1,

$$\omega_z = \frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} = -10$$

we conclude that, for the lower half of the flow at section 2,

$$\frac{\partial u}{\partial y} = 10.$$

This means the velocity profile at section 2 is a straight line with the same slope of the profile at section 1. Since we are neglecting viscosity, the flow can slip at the wall with a slip velocity  $u_0$ ; hence, the velocity distribution at section 2 is

$u_2(y) = u_0 + 10y$ . Continuity then allows us to calculate the profile:

$$V_1 A_1 = V_2 A_2$$

$$\frac{1}{2} (10 \times 0.04)(0.04w) = (u_0 + 10 \times 0.02/2)(0.02w). \quad \therefore u_0 = 0.3 \text{ m/s.}$$

Finally,

$$u_2(y) = \underline{0.3 + 10y}$$

5.43 No. The first of Eqs. 5.3.24 shows that, neglecting viscous effects,

$$\frac{D\mathbf{w}_x}{Dt} = \mathbf{w}_x \frac{\mathcal{J}u}{\mathcal{J}x} + \mathbf{w}_y \frac{\mathcal{J}u}{\mathcal{J}y} + \mathbf{w}_z \frac{\mathcal{J}u}{\mathcal{J}z}$$

so that  $\mathbf{w}_y$ , which is nonzero near the snow surface, creates  $\mathbf{w}_x$  through the term  $\mathbf{w}_y \mathcal{J}u / \mathcal{J}y$ , since there would be a nonzero  $\partial u / \partial y$  near the tree.

$$\begin{aligned} 5.44 \quad \int_{c.s.} k\bar{V}T \cdot \hat{n}dA &= \int_{c.v.} \frac{\partial}{\partial t} \left( \frac{V^2}{2} + gz + \bar{u} \right) \rho dV + \int_{c.s.} \left( \frac{V^2}{2} + gz + \bar{u} + \frac{p}{\rho} \right) \rho \bar{V} \cdot \hat{n}dA \\ \int_{c.v.} \bar{V} \cdot (k\bar{V}T) dV &= \int_{c.v.} \frac{\partial}{\partial t} \left( \frac{V^2}{2} + gz + \bar{u} \right) \rho dV + \int_{c.v.} \bar{V} \cdot \rho \bar{V} \left( \frac{V^2}{2} + gz + \bar{u} + \frac{p}{\rho} \right) dV \\ \therefore \int_{c.v.} \left[ -k\nabla^2 T + \frac{\partial}{\partial t} \left( \rho \frac{V^2}{2} + \rho gz + \rho \bar{u} \right) + \bar{V} \cdot \rho \bar{V} \left( \frac{V^2}{2} + gz + \bar{u} + \frac{p}{\rho} \right) \right] dV &= 0. \\ \frac{\mathcal{J}}{\mathcal{J}t} \mathbf{r} \frac{V^2}{2} + \bar{V} \cdot \mathbf{r} \bar{V} \left( \frac{V^2}{2} + gz + \frac{p}{\rho} \right) &= \frac{V^2}{2} \left( \frac{\mathcal{J}\mathbf{r}}{\mathcal{J}t} + \bar{V} \cdot \mathbf{r} \bar{V} \right) + \mathbf{r} \bar{V} \cdot \left[ \frac{\mathcal{J}\bar{V}}{\mathcal{J}t} + \bar{V} \cdot \nabla \bar{V} + \frac{\bar{V}p}{\mathbf{r}} + g\bar{V}_z \right] = 0. \\ &\quad \text{continuity} \qquad \qquad \qquad \text{momentum} \\ \therefore -k\nabla^2 T + \frac{\partial}{\partial t} \rho \bar{u} + \rho \bar{V} \cdot \bar{V} \bar{u} &= 0. \quad \therefore \rho \frac{D\bar{u}}{Dt} = k\nabla^2 T. \end{aligned}$$

5.45 Divide each side by  $dx dy dz$  and observe that

$$\frac{\frac{\partial T}{\partial x} \Big|_{x+dx} - \frac{\partial T}{\partial x} \Big|_x}{dx} = \frac{\partial^2 T}{\partial x^2}, \quad \frac{\frac{\partial T}{\partial y} \Big|_{y+dy} - \frac{\partial T}{\partial y} \Big|_y}{dy} = \frac{\partial^2 T}{\partial y^2}, \quad \frac{\frac{\partial T}{\partial z} \Big|_{z+dz} - \frac{\partial T}{\partial z} \Big|_z}{dz} = \frac{\partial^2 T}{\partial z^2}$$

Eq. 5.4.5 follows.

$$5.46 \quad \mathbf{r} \frac{D\bar{u}}{Dt} = \mathbf{r} \frac{D(h - p/\rho)}{Dt} = \mathbf{r} \frac{Dh}{Dt} - \frac{Dp}{Dt} + \frac{p}{\rho} \frac{D\mathbf{r}}{Dt} = \mathbf{r} \frac{Dh}{Dt} - \frac{Dp}{Dt} + \frac{p}{\rho} [-\mathbf{r}\nabla \cdot \bar{V}]$$

where we used the continuity equation:  $D\mathbf{r}/Dt = -\mathbf{r}\nabla \cdot \bar{V}$ . Then Eq. 5.4. 9 becomes

$$\mathbf{r} \frac{Dh}{Dt} - \frac{Dp}{Dt} + \frac{p}{\rho} [-\mathbf{r}\nabla \cdot \bar{V}] = K\nabla^2 T - p\nabla \cdot \bar{V}$$

which is simplified to

$$\mathbf{r} \frac{Dh}{Dt} = K\nabla^2 T + \frac{Dp}{Dt}$$

5.47 See Eq. 5.4.9:  $\bar{u} = cT$ .  $\therefore \rho c \left( \frac{\partial T}{\partial t} + u \frac{\partial T}{\partial x} + v \frac{\partial T}{\partial y} + w \frac{\partial T}{\partial z} \right) = k \nabla^2 T$ .

Neglect terms with velocity:  $\underline{\rho c \frac{\partial T}{\partial t} = k \nabla^2 T}$ .

5.48 The dissipation function  $\Phi$  involves viscous effects. For flows with extremely large velocity gradients, it becomes quite large. Then

$$r c_p \frac{DT}{Dt} = \Phi$$

and  $\frac{DT}{Dt}$  is large. This leads to very high temperatures on reentry vehicles.

5.49  $u = 10(1 - 10\,000 r^2)$ .  $\therefore \frac{\partial u}{\partial r} = -2r \times 10^5$ . ( $r$  takes the place of  $y$ )

From Eq. 5.4.17,  $\Phi = 2\mu \left[ \frac{1}{2} \left( \frac{\partial u}{\partial y} \right)^2 \right] = \mu 4r^2 \times 10^{10}$ .

At the wall where  $r = 0.01$  m,  $\Phi = 1.8 \times 10^{-5} \times 4 \times 0.01^2 \times 10^{10} = \underline{72 \text{ N} / \text{m}^2 \cdot \text{s}}$ .

At the centerline  $\frac{\partial u}{\partial r} = 0$  so  $\Phi = \underline{0}$ .

At a point half-way:  $\Phi = 1.8 \times 10^{-5} \times 4 \times 0.005^2 \times 10^{10} = \underline{18 \text{ N} / \text{m}^2 \cdot \text{s}}$ .

5.50 (a) Momentum:  $\frac{\partial u}{\partial t} = \nu \frac{\partial^2 u}{\partial y^2}$

Energy:  $\rho c \frac{\partial T}{\partial t} = K \frac{\partial^2 T}{\partial y^2} + \mu \left( \frac{\partial u}{\partial y} \right)^2$ .

(b) Momentum:  $\rho \frac{\partial u}{\partial t} = \mu \frac{\partial^2 u}{\partial y^2} + \frac{\partial \mu}{\partial y} \frac{\partial u}{\partial y}$

Energy:  $\rho c \frac{\partial T}{\partial t} = K \frac{\partial^2 T}{\partial y^2} + \mu \left( \frac{\partial u}{\partial y} \right)^2$ .